## IEEE Microchips and Dip

000

Workshop 1 – Building the Circuit

## Workshops Overview

Workshop 1 – Building the circuit:

- Design requirements
- STM32 Microcontroller
- Picking components and reading data sheets
- Drawing a schematic using KiCAD
- Assembling the circuit
- Running Hello World on STM32

Workshop 2 – Intro to Embedded:

- Introduction to embedded software
- How to use the MCU datasheet
- Hardware Abstraction Layer
- Reading ADC (Temperature sensor)

Workshop 3 – Communication protocols and FreeRTOS:

- Intro to I2C
- Reading accelerometer data
- Intro to FreeRTOS
- Multi-tasking on a single core with FreeRTOS
- External resources

## What is an embedded systems?



A computer system that involves, processor(s), memory, sensor, and other peripheral I/O devices.



This computer system performs a dedicated task, not a general purpose computer.

These systems don't consume a lot of power compared to a desktop computer (Milliwatts compared to watts)









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ENTER

OPSMAP 66





## Embedded system vs desktop computer

- No filesystem or operating system
- Less than 1 Mb RAM
- 16-300 Mhz CPU
- No screen/monitor to display data
- 50 cents to 5 dollar cost
- Does a few specific task very well
- Consumes milliwatts



- Filesystem or operating system
- A few Gbs of RAM
- 2-4 Ghz CPU
- Has a screen/monitor to display data
- A few hundred dollars
- Multi-purpose
- Consumes hundreds of watts



## What are our requirements

The system must collect temperature every second

The system must collect acceleration every 100 ms

The system must display this data somewhere



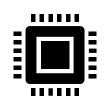
Selecting Parts for Our System



#### Accelerometer

Needs to be able to measure acceleration in 3 axis

**Temperature Sensor** Needs to be able to measure temperature within our required temperature range



#### Microcontroller

Needs to be able to communicate with sensor using digital protocols or analog signals

## Microcontroller Selection



# MICROCHIP

## STM32 Nucleo

#### NUCLEO-L432KC

Life, augmented



| Mouser #:        | 511-NUCLEO-L432KC  |   |
|------------------|--|---|
| Mfr. #:          | NUCLEO-L432KC  |   |
| Mfr.:            | STMicroelectronics   |   |
| Customer #:      | Customer # Ad  | d |
| Description:     | Development Boards & Kits - ARM STM3<br>Nucleo-32 dev board STM32L432KC,<br>supports Arduino nano conn | 2 |
| Datasheet:       | NUCLEO-L432KC Datasheet (PDF)  |   |
| More Information | Learn more about STMicroelectronics<br>NUCLEO-L432KC   |   |

| In Stock: 1,540         |                         |                      |
|-------------------------|-------------------------|----------------------|
| Stock:                  | 1,540 Can Ship I        | mmediately           |
| On Order:               | 4,050 Expected 2        | 23-Jan-23            |
| Factory Lead-Time:      | 35 Weeks ?              |                      |
| Long lead time reported | on this product.        |                      |
| Enter Quantity:         | Minimum: 1 Multiples: 7 | 1 Maximum: 10<br>Buy |
| Pricing (CAD)           |                         |                      |
| Qty.                    | Unit Price              | Ext. Price           |
| 1                       | \$14.26                 | \$14.26              |

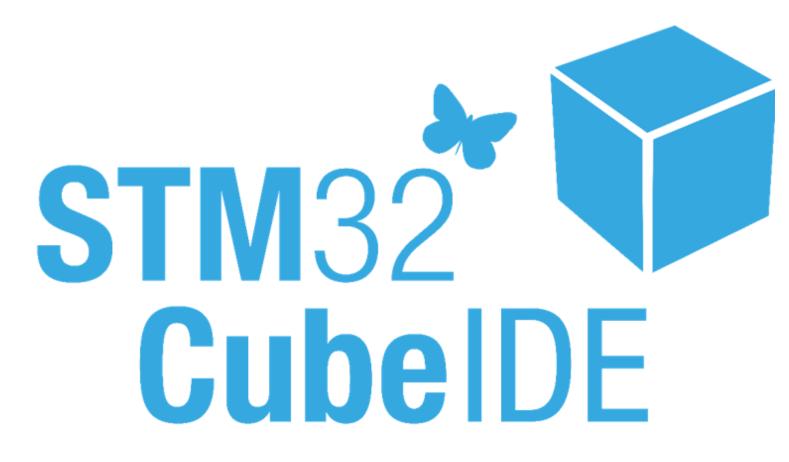


## Specification

#### All features

- Ultra-low-power with FlexPowerControl
  - 1.71 V to 3.6 V power supply
  - -40 °C to 85/105/125 °C temperature range
  - 8 nA Shutdown mode (2 wakeup pins)
  - 28 nA Standby mode (2 wakeup pins)
  - 280 nA Standby mode with RTC
  - 1.0 µA Stop 2 mode, 1.28 µA with RTC
  - 84 µA/MHz run mode
  - Batch acquisition mode (BAM)
  - 4 µs wakeup from Stop mode
  - Brown out reset (BOR)
  - Interconnect matrix
- Core: Arm<sup>®</sup> 32-bit Cortex<sup>®</sup>-M4 CPU with FPU, Adaptive real-time accelerator (ART Accelerator<sup>™</sup>) allowing 0-wait-state execution from Flash memory, frequency up to 80 MHz, MPU, 100DMIPS and DSP instructions
- Performance benchmark
  - 1.25 DMIPS/MHz (Drystone 2.1)
  - 273.55 CoreMark<sup>®</sup> (3.42 CoreMark/MHz @ 80 MHz)

- Memories
  - Up to 256 KB single bank Flash, proprietary code readout protection
  - 64 KB of SRAM including 16 KB with hardware parity check
  - Quad SPI memory interface
- Rich analog peripherals (independent supply)
  - 1x 12-bit ADC 5 Msps, up to 16-bit with hardware oversampling, 200 µA/Msps
  - 2x 12-bit DAC output channels, low-power sample and hold
  - 1x operational amplifier with built-in PGA
  - 2x ultra-low-power comparators
- 14x communication interfaces
  - USB 2.0 full-speed crystal less solution with LPM and BCD
  - 1x SAI (serial audio interface)
  - 2x I2C FM+(1 Mbit/s), SMBus/PMBus
  - 3x USARTs (ISO 7816, LIN, IrDA, modem)
  - 1x LPUART (Stop 2 wake-up)
  - 2x SPIs (and 1x Quad SPI)
  - CAN (2.0B Active)

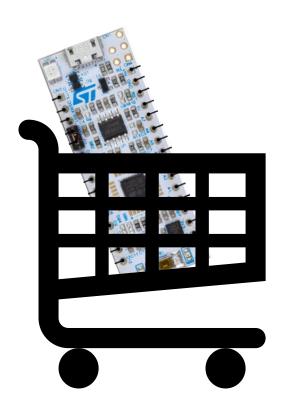


## Installing the STM32CUBE IDE

- STM32CUBE IDE is STM's development environment for their microcontrollers
- Compilers
- Debugging tools (break points, memory visualization)
- Pin assignment user interface
- Board upload tools
- Hardware Abstraction Layer (SDK for STM32s)
- <u>https://www.st.com/en/d</u>
   <u>evelopment-</u>
   <u>tools/stm32cubeide.html</u>

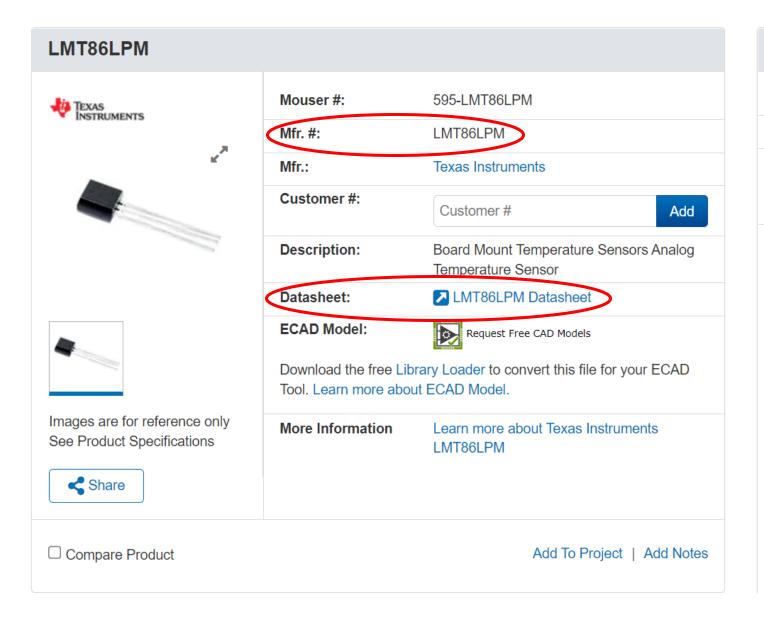
## Summary of STM32l432

- Available (sufficient quantity for our need)
- Comes in a development board
- Complete IDE
- Good specs
  - RAM
  - FLASH Memory
  - Sufficient inputs and outputs



## Temperature sensor

#### Order online in 04:33:02 to ship today. Shipping Details



| In Stock: 3,786         |                            |            |  |  |  |  |
|-------------------------|----------------------------|------------|--|--|--|--|
| Stock:                  | 3,786 Can Ship Immediately | >          |  |  |  |  |
| Factory Lead-Time:      | 6 Weeks ?                  |            |  |  |  |  |
| Enter Quantity:         | Minimum: 1 Multiples: 1    | Buy        |  |  |  |  |
| Pricing (CAD)           |                            |            |  |  |  |  |
| Qty.                    | Unit Price                 | Ext. Price |  |  |  |  |
| Cut Tape / MouseReel™ † |                            |            |  |  |  |  |
|                         | \$1.15                     | \$1.15     |  |  |  |  |
| 10                      | \$0.951                    | \$9.51     |  |  |  |  |
| 25                      | \$0.835                    | \$20.88    |  |  |  |  |
| 50                      | \$0.694                    | \$34.70    |  |  |  |  |
| 100                     | \$0.591                    | \$59.10    |  |  |  |  |
| 500                     | \$0.513                    | \$256.50   |  |  |  |  |
| 1,000                   | \$0.396                    | \$396.00   |  |  |  |  |
| Full Reel (Order in mu  | Ittiples of 2000)          |            |  |  |  |  |
| 2,000                   | \$0.395                    | \$790.00   |  |  |  |  |

## Datasheet





🔪 🚽 Order

Now

Technical Documents Support & Community

LMT86

SNIS169E - MARCH 2013-REVISED OCTOBER 2017

#### LMT86 2.2-V, SC70/TO-92/TO-92S, Analog Temperature Sensors

#### 1 Features

- LMT86LPG (TO-92S package) has a Fast Thermal Time Constant, 10-s Typical (1.2 m/s Airflow)
- Very Accurate: ±0.4°C Typical
- Low 2.2-V Operation
- Average Sensor Gain of -10.9 mV/°C
- Low 5.4-µA Quiescent Current
- Wide Temperature Range: -50°C to 150°C
- Output is Short-Circuit Protected
- Push-Pull Output With ±50-µA Drive Capability
- Footprint Compatible With the Industry-Standard LM20/19 and LM35 Temperature Sensors
- Cost-Effective Alternative to Thermistors

#### 2 Applications

- Infotainment and Cluster
- Powertrain Systems
- Smoke and Heat Detectors
- Drones
- Appliances

#### 3 Description

🔌 🖉 🕹

Software

The LMT86 are precision CMOS temperature sensors with  $\pm 0.4^{\circ}$ C typical accuracy ( $\pm 2.7^{\circ}$ C maximum) and a linear analog output voltage that is inversely proportional to temperature. The 2.2-V supply voltage operation, 5.4-µA quiescent current, and 0.7-ms power-on time enable effective power-cycling architectures to minimize power consumption for battery-powered applications such as drones and sensor nodes. The LMT86LPG through-hole TO-92S package fast thermal time constant supports offboard time-temperature sensitive applications such as smoke and heat detectors. The accuracy over the wide operating range and other features make the LMT86 an excellent alternative to thermistors.

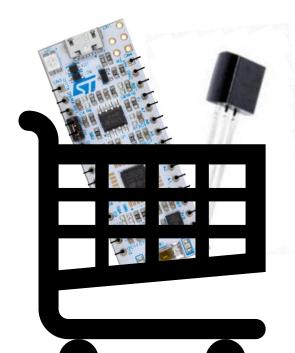
For devices with different average sensor gains and comparable accuracy, refer to *Comparable Alternative Devices* for alternative devices in the LMT8x family.

#### Device Information<sup>(1)</sup>

| PART NUMBER | PACKAGE   | BODY SIZE (NOM)   |
|-------------|-----------|-------------------|
| LMT86       | SOT (5)   | 2.00 mm × 1.25 mm |
|             | TO-92 (3) | 4.30 mm × 3.50 mm |

 For all available packages, see the orderable addendum at the end of the data sheet.

## Electrical Characteristics



#### 7.1 Absolute Maximum Ratings

See (1)(2)

|   | MIN  | MAX                     | UNIT |
|---|------|-------------------------|------|
| Supply voltage                                    | -0.3 | 6                       | V    |
| Voltage at output pin                             | -0.3 | (V <sub>DD</sub> + 0.5) | V    |
| Output current                                    | -7   | 7                       | mA   |
| Input current at any pin <sup>(3)</sup>           | -5   | 5                       | mA   |
| Maximum junction temperature (T <sub>JMAX</sub> ) |      | 150                     | °C   |
| Storage temperature, T <sub>stg</sub>             | -65  | 150                     | °C   |

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability

(2) Soldering process must comply with TI's Reflow Temperature Profile specifications. Refer to www.ti.com/packaging. Reflow temperature profiles are different for lead-free and non-lead-free packages.

(3) When the input voltage ( $V_1$ ) at any pin exceeds power supplies ( $V_1 < GND$  or  $V_1 > V$ ), the current at that pin should be limited to 5 mA.

#### 7.2 ESD Ratings

|                              |  |  | VALUE | UNIT |  |
|------------------------------|--|--|-------|------|--|
| LMT86L                       | P in TO-92 package   |  |       |      |  |
| V                            | Electrostatic  | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)(2)</sup>           | ±2500 | V    |  |
| V <sub>(ESD)</sub> discharge |  | Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(3)</sup> | ±1000 | v    |  |
| LMT86D                       | OCK in SC70 package  |  |       |      |  |
| V                            | Electrostatic  | Human-body model (HBM), per JESD22-A114 <sup>(2)</sup>                         | ±2500 | V    |  |
| V <sub>(ESD)</sub> discharge | Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(3)</sup> | ±1000  | v     |      |  |

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) The human body model is a 100-pF capacitor discharged through a 1.5-kΩ resistor into each pin.

(3) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

#### 7.3 Recommended Operating Conditions

|                                   | MIN                           | MAX | UNIT |
|-----------------------------------|-------------------------------|-----|------|
| Specified temperature             | $T_{MIN} \le T_A \le T_{MAX}$ |     | °C   |
| Specified temperature             | −50 ≤ T <sub>A</sub> ≤ 150    |     | °C   |
| Supply voltage (V <sub>DD</sub> ) | 2.2                           | 5.5 | V    |

## Accelerometer

#### SEN0409







Images are for reference only See Product Specifications



Compare Product

| Mouser #:        | 426-SEN0409  |
|------------------|--|
| Mfr. #:          | SEN0409  |
| Mfr.:            | DFRobot  |
| Customer #:      | Customer #   |
| Description:     | Acceleration Sensor Development Tools<br>Gravity: I2C LIS2DW12 Triple Axis<br>Accelerometer Sensor<br>(+/-2g/+/-4g/+/-8g/+/-16g) |
| Lifecycle:       | New Product: New from this manufacturer.   |
| More Information | Learn more about DFRobot SEN0409   |

Compare Product

Add To Project | Add Notes

# In Stock: 65Stock:65 Can Ship ImmediatelyFactory Lead-Time:6 Weeks ?Enter Quantity:Minimum: 1 Multiples: 1BuyPricing (CAD)Qty.Unit PriceExt. Price1\$5.38\$5.38

#### FEATURED PRODUCTS DFROBOT



#### Fermion I2C H3LIS200DL Triple Axis Accelerometer

Features low noise and large scale ranges, and ultra-low-power operational modes. Learn More

#### **Specifications**

## Datasheet

Datasheet

MEMS digital output motion sensor: high-performance ultra-low-power 3-axis "femto" accelerometer



#### Features

- Ultra-low power consumption: 50 nA in power-down mode, below 1 µA in active low-power mode
- Very low noise: down to 1.3 mg RMS in low-power mode
- · Multiple operating modes with multiple bandwidths
- Android stationary detection, motion detection
- Supply voltage, 1.62 V to 3.6 V
- Independent IO supply
- ±2a/±4a/±8a/±16a full scale
- High-speed I<sup>2</sup>C/SPI digital output interface
- Single data conversion on demand
- 16-bit data output
- Embedded temperature sensor
- Self-test
- 32-level FIFO
- 10000 g high shock survivability
- ECOPACK, RoHS and "Green" compliant



# We have our parts. Let's design the circuit!

We'll use design software to draw up the circuit!

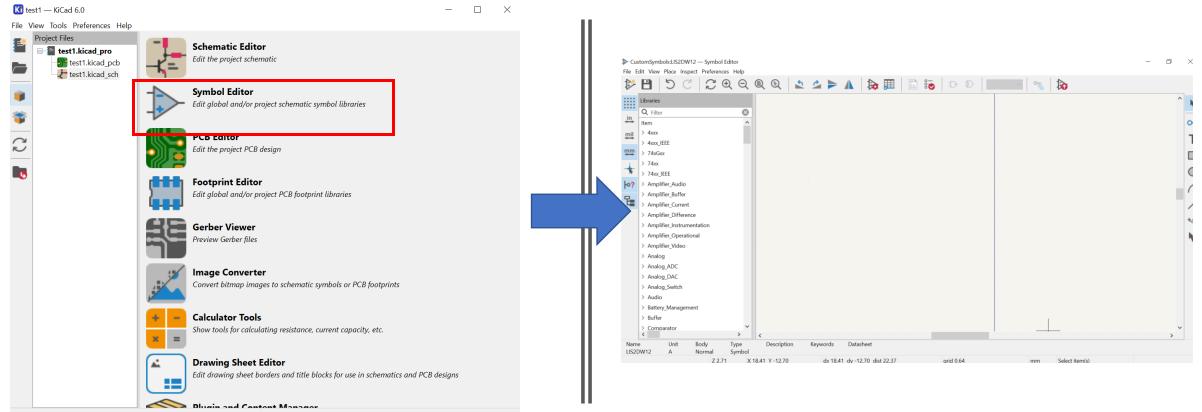


# Designing the circuit with KiCAD

- KiCAD is an open source circuit design tool used for making electrical schematics and printed circuit boards (PCBs)
- We will be using it for designing a schematic
- <u>https://www.kicad.org/download/</u>

## Creating Symbols

Not all parts have a pre-made symbol, we need to make symbols for our sensors



Project: C:\Users\mingy\Documents\M...ochipsAndDips\test1\test1.kicad... Local path: monitoring folder changes

#### Creating the Symbol (Continued)

#### File >> New Library

| Add To Library Table                     | ×       |
|--|---------|
| Choose the Library Table to add the libr | ary to: |
| Global                                   | ^       |
| Project                                  | $\sim$  |
| OK Can                                   | icel    |

Press OK

## Find a folder to save the symbols in (create a new folder if needed)

| KiCad > 6.0 > symbols V                 | ${\sim}$ Search symbols           |
|---|-----------------------------------|
| folder                                  |                                   |
| Name                                    | Date modified 11/12/2022 12:41 AM |
| n                                       |                                   |
| × <                                     | >                                 |
| AySymbols                               | Υ.                                |
| iCad symbol library files (*.kicad_sym) | ~                                 |
| [                                       | Save Cancel                       |

#### Creating the Symbol (Continued)

#### Select the Symbol Library

| CustomSymbols:LIS2DW12 — Sym       | nbol Edito | r   |     |   |   |  |   |   |
|------------------------------------|------------|-----|-----|---|---|--|---|---|
| File Edit View Place Inspect Prefe |            |     |     |   |   |  |   | 1 |
| ) 🔁 🖸 C 🖸                          | ;⊕         | Q ( | R Q | 5 | 0 |  | Þ |   |
| Libraries                          |            |     |     |   |   |  |   |   |
| C Filter                           |            |     |     |   |   |  |   |   |
| in Item ^                          |            |     |     |   |   |  |   |   |
| > Memory_UniqueID                  |            |     |     |   |   |  |   |   |
| Motor > Motor                      |            |     |     |   |   |  |   |   |
| MySymbols                          |            |     |     |   |   |  |   |   |
| > Oscillator                       |            |     |     |   |   |  |   |   |
| + > Potentiometer_Digital          |            |     |     |   |   |  |   |   |
| > power                            |            |     |     |   |   |  |   |   |
| > Power_Management                 |            |     |     |   |   |  |   |   |
| Power_Protection                   |            |     |     |   |   |  |   |   |
| > Power_Supervisor                 |            |     |     |   |   |  |   |   |
| > pspice                           |            |     |     |   |   |  |   |   |
| Reference_Current                  |            |     |     |   |   |  |   |   |
| > Reference_Voltage                |            |     |     |   |   |  |   |   |
| Regulator_Controller               |            |     |     |   |   |  |   |   |
| Regulator_Current                  |            |     |     |   |   |  |   |   |
| Regulator_Linear                   |            |     |     |   |   |  |   |   |
| Regulator_SwitchedCapa             |            |     |     |   |   |  |   |   |
| Regulator_Switching                |            |     |     |   |   |  |   |   |
| > Relay                            |            |     |     |   |   |  |   |   |
| > Relay SolidState                 |            |     |     |   |   |  |   |   |

#### File >> New Symbol

#### Give the symbol a name

| New Symbol   |                       |    |          | $\times$ |
|--|-----------------------|----|----------|----------|
| Symbol name:   | LMT8                  | 36 |          |          |
| Derive from existing symb  | ol:                   |    |          | ~        |
| Default reference designat   | or: U                 |    |          |          |
| Number of units per packa  | ge: 1                 |    |          | ▲<br>▼   |
| <ul> <li>Units are not interchang</li> <li>Create symbol with alter</li> <li>Create symbol as power</li> <li>Exclude from schematic</li> <li>Exclude from board</li> </ul> | rnate bod<br>r symbol |    | (De Morg | an)      |
| Pin name position offset:  | 0.508                 |    |          | mm       |
| $\checkmark$ Show pin number text  |                       |    |          |          |
| Show pin name text   |                       |    |          |          |
| 🗹 Pin name inside  |                       |    |          |          |
|  | OK                    |    | Cance    | el       |

#### Creating the Symbol (Continued)

#### Select the Symbol Library

| CustomSymbols:LIS2DW12 — Syr      | mbol Edito | or |   |   |   |   |  |   |  |
|-----------------------------------|------------|----|---|---|---|---|--|---|--|
| File Edit View Place Inspect Pref |            |    |   |   |   |   |  |   |  |
| ▶ ■ 5 C                           | € £        | Q  | Q | R | 5 | C |  | D |  |
| Libraries                         |            |    |   |   |   |   |  |   |  |
| 🗰 Q Filter 🛞                      |            |    |   |   |   |   |  |   |  |
| in Item ^                         |            |    |   |   |   |   |  |   |  |
| > Memory_UniqueID                 |            |    |   |   |   |   |  |   |  |
| Motor > Motor                     |            |    |   |   |   |   |  |   |  |
| mm ✓ MySymbols                    |            |    |   |   |   |   |  |   |  |
| > Oscillator                      |            |    |   |   |   |   |  |   |  |
| + > Potentiometer_Digital         |            |    |   |   |   |   |  |   |  |
| > power                           |            |    |   |   |   |   |  |   |  |
| Power_Management                  |            |    |   |   |   |   |  |   |  |
| Power_Protection                  |            |    |   |   |   |   |  |   |  |
| > Power_Supervisor                |            |    |   |   |   |   |  |   |  |
| > pspice                          |            |    |   |   |   |   |  |   |  |
| Reference_Current                 |            |    |   |   |   |   |  |   |  |
| Reference_Voltage                 |            |    |   |   |   |   |  |   |  |
| Regulator_Controller              |            |    |   |   |   |   |  |   |  |
| Regulator_Current                 |            |    |   |   |   |   |  |   |  |
| Regulator_Linear                  |            |    |   |   |   |   |  |   |  |
| > Regulator_SwitchedCapa          |            |    |   |   |   |   |  |   |  |
| > Regulator_Switching             |            |    |   |   |   |   |  |   |  |
| > Relay                           |            |    |   |   |   |   |  |   |  |
| > Relay SolidState                |            |    |   |   |   |   |  |   |  |

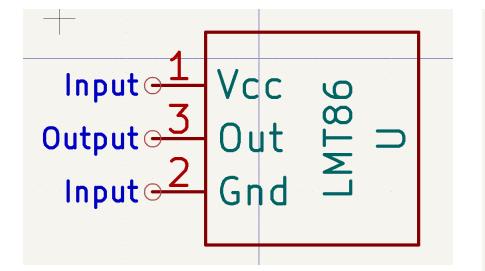
#### File >> New Symbol

#### Give the symbol a name

| New Symbol  |       |       | $\times$ |  |  |  |  |  |  |  |
|---|-------|-------|----------|--|--|--|--|--|--|--|
| Symbol name:  | LMT86 | LMT86 |          |  |  |  |  |  |  |  |
| Derive from existing symb   | ol:   |       | $\sim$   |  |  |  |  |  |  |  |
| Default reference designat  | or: U | U     |          |  |  |  |  |  |  |  |
| Number of units per packa   | ge: 1 | 1     |          |  |  |  |  |  |  |  |
| <ul> <li>Units are not interchangeable</li> <li>Create symbol with alternate body style (De Morgan)</li> <li>Create symbol as power symbol</li> <li>Exclude from schematic bill of materials</li> <li>Exclude from board</li> </ul> |       |       |          |  |  |  |  |  |  |  |
| Pin name position offset:   |       | mm    |          |  |  |  |  |  |  |  |
| $\checkmark$ Show pin number text   |       |       |          |  |  |  |  |  |  |  |
| Show pin name text  |       |       |          |  |  |  |  |  |  |  |
| 🗹 Pin name inside   |       |       |          |  |  |  |  |  |  |  |
|   | ОК    |       | Cancel   |  |  |  |  |  |  |  |

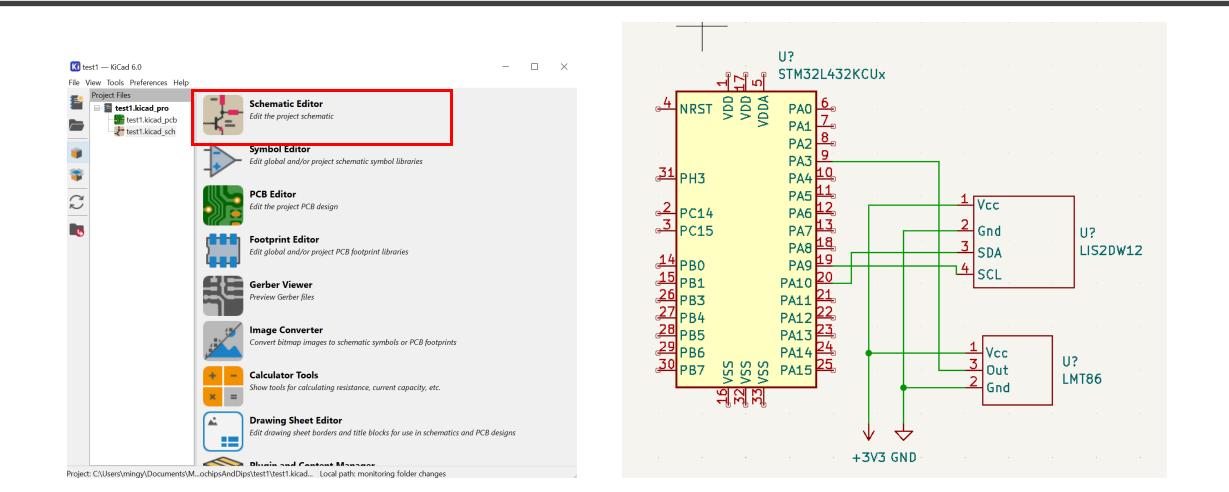


Add the pins and create the symbol. Refer to the data sheet for specifics



Inputo Vcc Inputo 2 Gnd Outputo 3 SDA Inputo 4 SCL LIS2DW12

## Creating the schematic



# Time to build the circuit

Please try not to reverse polarity anything :)

# Hello World! Blinking an LED

Let's get the LED on the Nucleo board to blink!